APPENDIX 1

```
void sw()
 5
                                                             /* instruction
             #define iw = 12;
                                                             width */
                                                             /* memory width */
             \#define mw = 3:
                                                             /* push constant */
             \#define CONST = 0
                                                             /* push variable */
             \#define LOAD = 1
10
                                                              /* push address */
             #define GLOBAL = 2
                                                            put a character along the
             #define PUTCHAR, = 15 /*
                                                             standard output channel*/
                                                             get a character from the
             #define GETCHAR = 16 /*
                                                             standard input channel */
15
             rom program []
             #include "prog.o" ): ram stack[1«mw] with dualport = 1 ];
20
             ram memory[1 < mw] unsigned iw PC, ir, tos;
             unsigned mw sp;
             do par it = program[pc]: PC = PC + 1;
                                                                /* save top of
             tos = stack[sp-1];
25
                                                                stack to avoid
                                                                two ram accesses
                                                                in one cycle
                                                                */
30
             switch (ir)
             case
             CONST par
                    stack[sp] = program[pc];
                    sP = sP+1:
35
                    PC = Pc+1:
                    break;
             case LOAD
40
                    stack[sp-1] = memory[tos < -mw];
                    break;
                                                                /* unknown opcode */
             case STOP break; default:
             while (1) delay;
45
             l while (ir != STOP);
```

]

Register transfer level description of simple processor

5

APPENDIX 2

```
void main() { char hwswchan; char unsigned 8 port:

5

par {
    parallel_,,port(port);
    SyncGen():

10

initialiseRam(port);
    par {
        display(hwswchan): sw(hwswchan);
        y 1 }

}

15

RTL description of main
```

APPENDIX 3

CALCULATION PROCESS

```
5
      * Channel communicating object positions
      */ chap unsigned 17 position;
      /*
      * Channel communicating segment information
10
      chanout unsigned 9 segment;
      * Channel communicating button information
15
      chanin unsigned 2 buttons;
      * Overall par
20
      */ par
              * Mass motion
              */
25
                  * Positions of each mass, 9+8 fixed point
                  unsigned 17 p0, p1, p2, p3, p4, p5, p6, p7;
30
                  * Velocity of each mass, 9+8 fixed point
                  int 17 vl, v2, v3, v4, v5, v6, v7; '
35
                  * Accelerations of each mass, 9+8 fixed point
                  int 17 al, a2, a3, a4, a5, a6, a7;
                  * Sutton status
40
                  unsigned 2 button status;
                  * Initial setup of positions
45
```

```
LCCESSO LECES
```

```
p0 = 65536;
                 pl = 65536;
                 p2 = 65536;
                 p3 = 65536;
 5
                 p4 = 65536;
                 p5 = 65536;
                 p6 = 65536
                 p7 = 65536
10
                  * Forever
                  */
                 while (1)
15
                    {
                     * Send successive positions down position channel
                    send(position, p0);
20
                    send(position, p1);
                    send(position, pl);
                    send(position, p2);
                    send(position, p2);
                    send(position, p3);
25
                    send (position, p3);
                    send(position, p4);
                    send(position, p4);
                    send(position, p5);
30
                    send(position, p5);
                    send(position, p6);
                    send(position, p6);
                    send(position, p7);
35
                    * Update positions according to velocities
                     */
                    pl +_ (unsigned 17)vl;
                    p2 + (unsigned 17)v2;
                    p3 + (unsigned 17)v3;
40
                    p4 + (unsigned 17)v4;
                    p5 + (unsigned 17)v5;
                    p6 + (unsigned 17)v6;
                    p7 + (unsigned 17)v7;
45
                     /*
```

```
* Update velocities according to accelerations
                      */
                     vl += al - (v1 > 6);
                     v2 += a2 - (v2 > 6);
                     v3 += a3 - (v3 > 6);
 5
                     v4 += a4 - (v4 > 6);
                     v5 += a5 - (v5' > 6);
                     v6 += a6 - (v6 > 6);
                     v7 += a7 - (v7 > 6);
10
                     /*
                       * Set accelerations according to relative positions
                     a1 = (int 17)(((p2 » 8) - (p1 » 8)) + ((p0 » 8) - (p1 » 8)));
                     a2 = (int 17)(((p3 \gg 8) - (p2 \gg 8)) + ((p1 \gg 8) - (p2 \gg 8))):
15
                     a3 = (int 17)!!(p4 \gg 8) - (p3 \gg 8)) + ((p2 \gg 8) - !p3 \gg 8)));
                     a4 = (int 17)(((p5 » 8) - (p4 » 8)) + ((p3 » 8) - (p4 » e) >;
                     a5 = (int 17)((!p6 » 8) - (p5 » 8)) + ((p4 » 8) - (p5 » 8)));
                     a6 = (int 17)(((p7 \gg 8) - (p6 \gg 8)) + ((p5 \gg 8) - (p6 \gg e >);
                     a7 = (int 17)((p6 » 8) - (p7 » 8));
20
                     /*
                       * Get button information
25
                     receive(buttons, button status);
                       * Fix top point according to buttons
                       */ if (button status & 1)
30
                        p0 = 65536 - 16384;
                         if (button status & 2)
               else
                           p0 = 65536 + 16384;
35
               else
                           p0 = 65536;
40
                )
                  * nine drawing
45
```

```
* Positions of previous and next massess positions
                 unsigned 17 prev .pos, next pos, curr pos;
                   * Which line of interpolation
 5
                 unsigned char line;
                   * Forever
                   */
10
                 while (1)
                     * Receive previous mass position
15
                    receive (position, prev posy;
                    curr pos = prev pos;
                      * Read next mass position
20
                    receive(position, next posy;
                      * Do 64 lines of interpolation
                    for (line = 0; line != 64; line++)
25
                       (
                           * Send start position of segment
                                                         /**width adjustment:17 along
                         send(segment, curr pos » 8);
30
                                                           channel of width 9 so takes bottom 9
                                                           bits*/
                           * Move by appropriate amount (1/64 total change)
35
                          curr pos + (unsigned 17)(((int 17)next pos -
                                                    (int 17)prev pos) » 6);
                           * Send end position of segment
40
                          send(segment, curr pos » 8):
                     )
               )
45
      )
```

DISPLAY PROCESS 5 /* standard includes */ #include "hammond.h" #include "syncgen.h" #include "stdlib.h" #include "parallel.h" 10 * Segment information channel */ chap segment; 15 * Button information channel */ chan buttons: * Include dash generated stuff */ 20 #include "handelc.h" * Main program */ 25 void main() (* Scan positions */ unsigned sx, sy; 30 * Vdeo output register unsigned 1 video; 35 * Video output bus */ interface bus out() video out(Visible(sx, sy)? (video ? (unsigned 12)Oxfff: 0) 0) with video spec; 40 #ifndef SIMULATE * Left button input bus 45 interface bus in (unsigned 1) button_left()

with button white spec;

```
* Right button input bus
 5
              interface bus in(unsigned 1) button right()
                 with button black spec;
            #endif
10
                  Overall par
      */ par {
                     * VGA sync generator
15
                    SyncGen(sx, sy, hsync pin, vsync pin);
                        Dash generated hardware
20
                    hardware();
                     * Run-length decoder
25
                     * Segment start and end positions
                    unsigned start, end;
30
                     * Forever
                    while (1)
35
                       {
                         while (sy != 448)
                             * Read segment information
                            segment? start;
40
                            segment? end;
                             * Get in the right order
45
                            if (start > end)
                               {
```

```
par
                                   {
     end = start;
5
     start = end;
     )
     * Make at least 1 pixel visible
10
      */
     if (start = end)
                             end++;
15
      /*
                             * Wait
      */
                           while (sx != 0)
                              delay;
20
                             * Draw a scanline worth
                           while (sx != 512)
                                if ((sx <- 9) >= start && (sx <- 9) < end)
25
                                   video = 1;
                                else
                              video = 0;
                              )
30
                           * Communicate button status
             #ifdef SIMULATE
35
                         buttons!1;
             #else
                          buttons! button left.in @ button right.in;
             #endif
                           * Wait
40
                         while (sy != 0)
                            delay;
                       )
45
```